

# Package: TMBhelper (via r-universe)

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**Type** Package

**Title** Package for basic helper functions that are not worth putting in  
a specialized contributed package

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**Description** Basic functions as suggested and contributed by users and  
not worth making a specific contributed R package

**Imports** abind, tmbstan

**License** GPL-3

**RoxxygenNote** 7.1.2

**Repository** <https://noaa-fims.r-universe.dev>

**RemoteUrl** [https://github.com/kaskr/TMB\\_contrib\\_R](https://github.com/kaskr/TMB_contrib_R)

**RemoteRef** HEAD

**RemoteSha** d275e5226d94a8b3b4b3417dbe89dac533d5f8c5

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`check_estimability`      *Check for identifiability of fixed effects*

### Description

`check_estimability` calculates the matrix of second-derivatives of the marginal likelihood w.r.t. fixed effects, to see if any linear combinations are not estimable (i.e. cannot be uniquely estimated conditional upon model structure and available data, e.g., resulting in a likelihood ridge and singular, non-invertable Hessian matrix)

### Usage

```
check_estimability(obj, h)
```

### Arguments

<code>obj</code>	The compiled object
<code>h</code>	optional argument containing pre-computed Hessian matrix

### Value

A tagged list of the hessian and the message

`Check_Identifiable`      *Copy of check\_estimability*

### Description

Included for continuity when using old scripts

### Usage

```
Check_Identifiable(...)
```

### Details

Please use `check_estimability` to see list of arguments and usage

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extract_fixed	<i>Extract fixed effects</i>
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### Description

`extract_fixed` extracts the best previous value of fixed effects, in a way that works for both mixed and fixed effect models

### Usage

```
extract_fixed(obj)
```

### Arguments

obj	The compiled object
-----	---------------------

### Value

A vector of fixed-effect estimates

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fit_tmb	<i>Optimize a TMB model</i>
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### Description

`fit_tmb` runs a TMB model and generates standard diagnostics

### Usage

```
fit_tmb(  
  obj,  
  fn = obj$fn,  
  gr = obj$gr,  
  startpar = NULL,  
  lower = -Inf,  
  upper = Inf,  
  getsd = TRUE,  
  control = list(eval.max = 10000, iter.max = 10000, trace = 1),  
  bias.correct = FALSE,  
  bias.correct.control = list(sd = FALSE, split = NULL, nsplit = NULL, vars_to_correct  
    = NULL),  
  savedir = NULL,  
  loopnum = 2,  
  newtonsteps = 0,  
  n = Inf,  
  getReportCovariance = FALSE,
```

```

getJointPrecision = FALSE,
getHessian = FALSE,
quiet = FALSE,
start_time_elapsed = as.difftime("0:0:0"),
...
)

```

## Arguments

<code>obj</code>	The compiled TMB object
<code>startpar</code>	Starting values for fixed effects (default NULL uses <code>obj\$par</code> )
<code>lower</code>	vectors of lower and upper bounds, replicated to be as long as <code>start</code> . If unspecified, all parameters are assumed to be unconstrained.
<code>upper</code>	vectors of lower and upper bounds, replicated to be as long as <code>start</code> . If unspecified, all parameters are assumed to be unconstrained.
<code>getsd</code>	Boolean indicating whether to run standard error calculation; see <a href="#">sdreport</a> for details
<code>control</code>	A list of control parameters. For details see <a href="#">nlminb</a>
<code>bias.correct</code>	Boolean indicating whether to do epsilon bias-correction; see <a href="#">sdreport</a> and <a href="#">fit_tmb</a> for details
<code>bias.correct.control</code>	tagged list of options for epsilon bias-correction, where <code>vars_to_correct</code> is a character-vector of ADREPORT variables that should be bias-corrected
<code>savedir</code>	directory to save results (if <code>savedir=NULL</code> , then results aren't saved)
<code>loopnum</code>	number of times to re-start optimization (where <code>loopnum=3</code> sometimes achieves a lower final gradient than <code>loopnum=1</code> )
<code>newtonsteps</code>	Integer specifying the number of extra newton steps to take after optimization (alternative to <code>loopnum</code> ). Each newtonstep requires calculating the Hessian matrix and is therefore slow. But for well-behaved models, each Newton step will typically decrease the maximum gradient of the loglikelihood with respect to each fixed effect, and therefore this option can be used to achieve an arbitrarily low final gradient given sufficient time for well-behaved models. However, this option will also perform strangely or have unexpected consequences for poorly-behaved models, e.g., when fixed effects are at upper or lower bounds.
<code>n</code>	sample sizes (if <code>n!=Inf</code> then <code>n</code> is used to calculate BIC and AICc)
<code>getReportCovariance</code>	Get full covariance matrix of ADREPORTed variables?
<code>getJointPrecision</code>	Optional. Return full joint precision matrix of random effects and parameters?
<code>getHessian</code>	return Hessian for usage in later code
<code>quiet</code>	Boolean whether to print additional messages results to terminal
<code>start_time_elapsed</code>	how much time has elapsed prior to calling <code>fit_tmb</code> , for use, e.g., when calling <code>fit_tmb</code> multiple times in sequence, where <code>start_time_elapsed = opt_previous\$time_for_run</code>
<code>...</code>	list of settings to pass to <a href="#">sdreport</a>

## Value

the standard output from `nlinnb`, except with additional diagnostics and timing info, and a new slot containing the output from `sdreport`

## References

For more details see <https://doi.org/10.1016/j.fishres.2015.11.016>

## Examples

```
TMBhelper::fit_tmb( Obj ) # where Obj is a compiled TMB object
```

---

### oneStepPredict\_deltaModel

*Calculate one-step-ahead (OSA) residuals for a mixed-effects delta-model.*

---

## Description

`oneStepPredict_deltaModel` is a wrapper for `oneStepPredict` for distributions with a mixture of discrete and continuous distributions

## Usage

```
oneStepPredict_deltaModel(obj, observation.name, deltaSupport = 0, ...)
```

## Arguments

<code>obj</code>	Output from <code>MakeADFun</code> .
<code>observation.name</code>	Character naming the observation in the template.
<code>deltaSupport</code>	integer-vector, listing values that have a dirac-delta within an otherwise continuous distribution
<code>...</code>	list of arguments to pass to <code>oneStepPredict</code>

## Details

It is convenient to compute one-step-ahead residuals for data that arise as a mixture of continuous and discrete distributions. One common example is a delta-model, which arises as a mixture of an encounter probability and a continuous distribution for biomass given an encounter. In these cases, it is possible to apply `oneStepPredict` twice, once for observations falling within the continuous domain, and again for observations in the discrete domain, and then combining the two. This function provides an example of doing so. It is designed to use the ‘method="cdf”’ feature in `oneStepPredict`, and code changes in the CPP side are shown in the example script ‘deltaModel.R’ loaded within directory ‘`system.file("tmb", package="TMBhelper")`’. This example also shows a proof-of-concept for uniform residuals under a (sufficiently-close-to) correctly specified model.

**Value**

the standard output from [oneStepPredict](#)

**Examples**

## Not run:

```
library(TMB)
library(RandomFields)
library(INLA) # FROM: http://www.r-inla.org/download

#####
# Poisson-link gamma distribution
#####

# n = numbers density
# w = weight-per-number
# cv = CV of gamma
dpoislinkgamma = function(x, n, w, cv){
  pow = function(a,b) a^b
  enc_prob = 1 - exp(-n)
  posmean = n * w / enc_prob
  if( x==0 ){
    dens = 1 - enc_prob
  }else{
    dens = enc_prob * dgamma(x, shape=pow(cv,-2), scale=posmean*pow(cv,2))
  }
  if(log==FALSE) return(dens)
  if(log==TRUE) return(log(dens))
}

ppoislinkgamma = function(x, n, w, cv){
  pow = function(a,b) a^b
  enc_prob = 1 - exp(-n)
  posmean = n * w / enc_prob
  dist = 1 - enc_prob
  if( x>0 ){
    posmean = n*w
    dist = dist + enc_prob * pgamma(x, shape=pow(cv,-2), scale=posmean*pow(cv,2))
  }
  return(dist)
}

rpoislinkgamma = function(n, w, cv){
  pow = function(a,b) a^b
  enc_prob = 1 - exp(-n)
  posmean = n * w / enc_prob
  enc = rbinom(n=1, prob=enc_prob, size=1)
  x = enc * rgamma(n=1, shape=pow(cv,-2), scale=posmean*pow(cv,2))
  return(x)
}

#####
# Simulate data
```

```

#####
Dim = c("n_x"=10, "n_y"=10)
loc_xy = expand.grid("x"=1:Dim['n_x'], "y"=1:Dim['n_y'])
Scale = 2
Sigma2 = (0.5) ^ 2
beta0 = 1
w = 1
cv = 0.1

# Simulate spatial process
RMmodel = RMgauss(var=Sigma2, scale=Scale)
epsilon_xy = array(RFsimulate(model=RMmodel, x=loc_xy[, 'x'], y=loc_xy[, 'y'])@data[, 1], dim=Dim)

# Simulate samples
c_xy = array(NA, dim=dim(epsilon_xy))
for(x in 1:nrow(c_xy)){
  for(y in 1:ncol(c_xy)){
    c_xy[x,y] = rpoislinkgamma( n=exp(beta0 + epsilon_xy[x,y]), w=w, cv=cv )
  }
}

#' #####
#' # SPDE-based
#####

# create mesh
mesh = inla.mesh.create( loc_xy, plot.delay=NULL, refine=FALSE)
# Create matrices in INLA
spde <- inla.spde2.matern(mesh, alpha=2)

# C0mpile
setwd( system.file("tmb", package="TMBhelper") )
compile( "deltaModel.cpp" )
dyn.load( dynlib("deltaModel") )

# Build object
Data = list("c_i"=as.vector(c_xy), "j_i"=mesh$idx$loc-1, "M0"=spde$param.inla$M0, "M1"=spde$param.inla$M1, "M2"=spde$param.inla$M2, "Params"=list( "beta0"=0, "ln_tau"=0, "ln_kappa"=0, "ln_w"=0, "ln_cv"=0, "epsilon_j"=rep(0,nrow(spde$param.inla$M0)) ), "Map"=list( "ln_tau"=factor(NA), "ln_kappa"=factor(NA), "epsilon_j"=factor(rep(NA,length(Params$epsilon_j))) ) )
Obj = MakeADFun( data=Data, parameters=Params, random="epsilon_j", map=Map )

# Optimize
Opt = TMBhelper::fit_tmb( obj=Obj, newtonsteps=0, getsd=FALSE )
report = Obj$report()

# Run
osa = oneStepPredict_deltaModel( obj=Obj, observation.name="c_i", method="cdf",
  data.term.indicator="keep", deltaSupport=0, trace=TRUE, seed=1 ) #discreteSupport = seq(0,max(Data$c_i),by=1) )
qqnorm(osa$residual); abline(0,1)

# should be uniform from 0 to mean(c_xy==0) when mapping off random effects
qresid = NULL
for(i in 1:1000){

```

```

osa = oneStepPredict_deltaModel( obj=Obj, observation.name="c_i", method="cdf",
  data.term.indicator="keep", deltaSupport=0, trace=FALSE, seed=i ) #discreteSupport = seq(0,max(Data$c_i),by=1)
qresid = c( qresid, pnorm(osa[which(Obj$env$data[["c_i"]]==0),'residual']) )
}

hist(qresid)
abline( v=mean(c_xy==0), lwd=3, lty="dotted" )

## End(Not run)

```

---

**Optimize***Copy of fit\_tmb***Description**

Included for continuity when using old scripts

**Usage**

```
Optimize(...)
```

**Details**

Please use ?fit\_tmb to see list of arguments and usage

**sample\_re***Sample random effects to correct for re-transformation bias***Description**

`sample_re` calculates MCMC samples of random effects conditional upon estimated MLE for fixed effects, and then uses each sample to calculate objects in the report. This is useful e.g., in correcting for re-transformation bias (by calculating the posterior mean of a nonlinear transformation of random effects) or visualizing random-effect variance (which often can be time-consuming using the delta-method in models with many random effects)

**Usage**

```

sample_re(
  obj,
  warmup = 50,
  iter = 150,
  report_names = NULL,
  dat = obj$env$data,
  ...
)

```

**Arguments**

<code>obj</code>	the TMB object after parameter estimation
<code>warmup</code>	A positive integer specifying the number of warmup (aka burnin) iterations per chain. If step-size adaptation is on (which it is by default), this also controls the number of iterations for which adaptation is run (and hence these warmup samples should not be used for inference). The number of warmup iterations should be smaller than <code>iter</code> and the default is <code>iter/2</code> .
<code>iter</code>	A positive integer specifying the number of iterations for each chain (including warmup). The default is 2000.
<code>report_names</code>	which elements of <code>obj\$report()</code> should be recorded; default <code>report_names=NULL</code> uses <code>report_names=names(obj\$report())</code>
<code>...</code>	adding arguments to pass to <code>tmbstan</code>

**Value**

A tagged list containing:

```
stan_out output from tmbstan
report_full A list of output from obj$report()[report_names], except with extra dimension
for each MCMC sample
run_time total run time
```

**References**

For a discussion of the epsilon-estimator as alternative method to correct for re-transformation bias  
see <https://doi.org/10.1016/j.fishres.2015.11.016>

TMBAIC

*Calculate marginal AIC for a fitted model***Description**

TMBAIC calculates AIC for a given model fit

**Usage**

```
TMBAIC(opt, p = 2, n = Inf)
```

**Arguments**

<code>opt</code>	the output from <code>nlinrb</code> or <code>optim</code>
<code>p</code>	the penalty on additional fixed effects (default=2, for AIC)
<code>n</code>	the sample size, for use in AICc calculation (default=Inf, for which AICc=AIC)

**Value**

AIC, where a parsimonious model has a AIC relative to other candidate models

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